

## Installation instructions

**i** For more information about drive installation, use and maintenance refer to user manual available at <http://www.everelettronica.it/manhw.html>



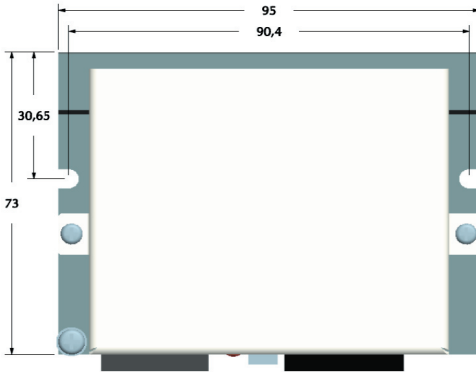
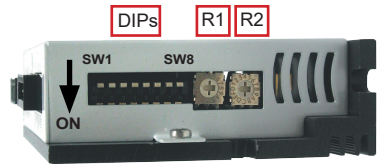
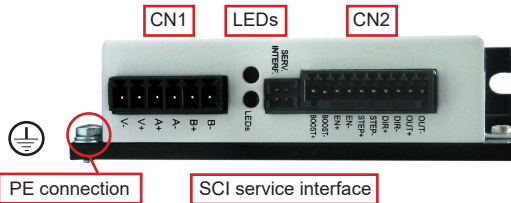
## 2 phase step motor bipolar chopper drive technical data

- DC power supply: 12 ± 36 Vdc
- Phase current: 0.14±4.2 Apeak
- Chopper frequency: ultrasonic 40KHz
- Emulated Step angle: Full Step, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128, 1/256, 1/5, 1/10, 1/25, 1/50, 1/125, 1/250 configurable by means of Roto-Switches
- Protections against: over current, over/under voltage, overheating, short circuit between motor phase-to-phase and phase-to-ground
- Service SCI interface for programming and real time debugging
- Dimensions: 95 x 73 x 26 mm (without connectors)
- Protection degree: IP20
- Pollution degree: 2
- Working temperature: 5°C + 40°C
- Storage temperature: -25°C + 55°C
- Humidity: 5% + 85% not condensing



**TITANIO**  
VECTOR - STEPPER - DRIVES

## Mechanical drawing and connections



### CN1: Power supply and Motor 6 position, pitch 3.81mm, PCB header connector

CN1.1	GND	PWR_IN	Power supply GND
CN1.2	V+	PWR_IN	Power supply Voltage
CN1.3	A	PWR_OUT	Motor Output phase A
CN1.4	A/	PWR_OUT	Motor Output phase A/
CN1.5	B	PWR_OUT	Motor Output phase B
CN1.6	B/	PWR_OUT	Motor Output phase B/

### CN2: Digital inputs and output 10 position, pitch 2.5mm, PCB header connector

CN2.1	Boost+	DIG_IN	Boost + input
CN2.2	Boost-	DIG_IN	Boost - input
CN2.3	EN+	DIG_IN	Enable + input
CN2.4	EN-	DIG_IN	Enable - input
CN2.5	Step+	DIG_IN	Clock frequency + input (Clock_up +)
CN2.6	Step-	DIG_IN	Clock frequency - input (Clock_up -)
CN2.7	Dir+	DIG_IN	Motor direction + input (Clock down +)
CN2.8	Dir-	DIG_IN	Motor direction - input (Clock down -)
CN2.9	Out+	PWR_IN	Positive 24Vdc power supply digital output
CN2.10	Out-	DIG_OUT	Open emitter FAULT output

## Dip-Switches Settings


Motor Phase Current (Apeak)	DIPs				Default
	SW1	SW2	SW3	SW4	
0.14	off	off	off	off	X
0.28	on	off	off	off	
0.56	off	on	off	off	
0.85	on	on	off	off	
1.10	off	off	on	off	
1.40	on	off	on	off	
1.70	off	on	on	off	
2.00	on	on	on	off	
2.30	off	off	off	on	
2.50	on	on	off	on	
2.80	off	on	off	on	
3.10	on	on	off	on	
3.40	off	off	on	on	
3.70	on	off	on	on	
4.00	off	on	on	on	
4.20	on	on	on	on	

DIP SW5	Current reduction range	Default
off	Idle current reduction to 70%	X
on	Idle current reduction to 30%	

DIP SW6	Drive enable polarity	Default
off	Enable Asserted = Drive Disable	X
on	Enable Asserted = Drive Enable	

DIP SW7	Drive Control Mode	Default
off	Step and Dir. mode	X
on	Clock_up / Clock_down mode	

DIP SW8	Reserved	Default
off	Reserved	X
on	Reserved	

 **NOTE:** the device reads the Dip-Switches only at powering up. If it's necessary a setting change, shut down the system, change the settings and start the up the system again to make the changes operating.


## Roto-Switch R1 settings (Step Resolution and Clock Test)

Position	Step angle
0	Full step
1	1/2 step
2	1/4 step (default)
3	1/8 step
4	1/16 step
5	1/32 step
6	1/64 step
7	1/128 step
8	1/256 step
9	1/5 step
A	1/10 step
B	1/25 step
C	1/50 step
D	1/125 step
E	1/250 step
F	Clock test

### Clock Test

To activate the clock test function set the Roto-switch R1 at F position, this function show with the led the clock signal frequency input. During the clock test the driver is disabled.

Clock [Hz]	Green	Red	Yellow
0	on	on	off
1<clock<1000	Blinking (200 ms)	off	on
clock≥1000	Blinking (200 ms)	on	off

 **NOTE:** the device reads the R1 Roto-Switches only at powering up. If it's necessary a setting change, shut down the system, change the settings and start the up the system again to make the changes operating.

## Roto-Switch R2 settings (Software defined)

Functionality of the Roto-Switch R2 is defined by software. Connect to PC on Service Interface connector.

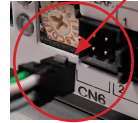
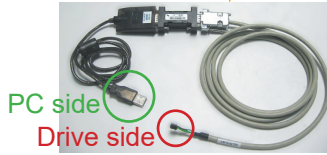
## Working status (LEDs)

Driver disabled: green blinking (1s)  
 Driver enabled: green on  
 Motor open phase: red on  
 Motor phase shortcut: red blinking (200 ms)  
 Over voltage: red on (2 sec) – yellow on (1 sec)  
 Under Voltage: red on (2 sec) – yellow on (1 sec) – yellow on (1 sec)  
 Over temperature: red on (2 sec) – yellow on (1 sec) – yellow on (1 sec) – yellow on (1 sec)

## Service SCI connection



This connection is **only** possible with hardware and software provided by Ever.  
Kit code: LW3\_SERV00-SL



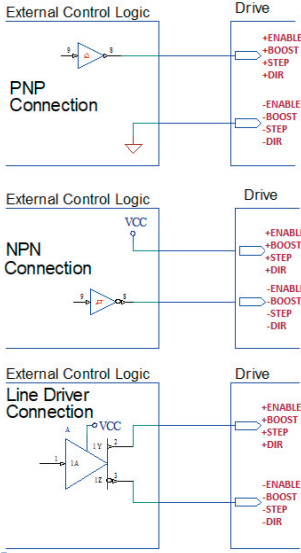
**ATTENTION!!!**  
Correct insertion direction of the CN6: TAB UP.

## Connection to the digital inputs



Differential PNP, NPN and Line Driver type.

### 5 - 24Vdc INPUTS

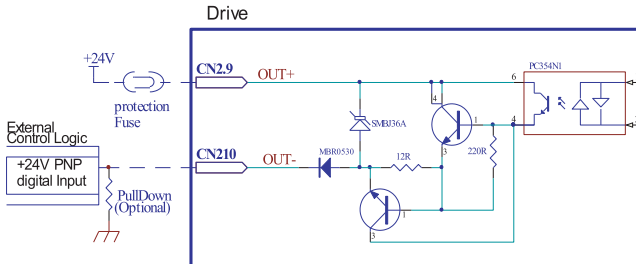


Standard (EN & BOOST)			
Characteristics	MIN.	MAX.	Unit
Supply Voltage	5	24	Vdc
Inputs Frequency	---	10	kHz
Threshold switching voltage	1.77	1.95	Vdc
Current at 5Vdc	---	5.4	mA
Current at 24 Vdc	---	8.4	mA

High speed (STEP & DIR)			
Characteristics	MIN.	MAX.	Unit
Supply Voltage	5	24	Vdc
Inputs Frequency	---	250	kHz
Threshold switching voltage	2.0	2.2	Vdc
Current at 5Vdc	---	5.4	mA
Current at 24 Vdc	---	8.4	mA

## Connection to the digital output

The output is sized to function at  $V_{OUTmax}=24Vdc$ ,  $I_{OUTmax}=100mA$  and it's protected from inversion of the polarity.  
OK = Transistor Output Closed - FAULT = Transistor Output Open



**Attention: the FAULT output is not protected in current.**  
Provide an external current limitation device ( $I_{OUTmax} = 100mA$ ).  
The protective device may be placed on the output power conductor +24VDC (CN2.10).

## Mating connectors


Connector	Description
CN1	Phoenix 1803617 (Green) or 1839652 (Black)
CN2	Phoenix 1881406 (Green) or 1700841 (Black)

## Cables section

Function	Cable	
	Minimum	Maximum
Power supply and PE	0.2 mm <sup>2</sup> (AWG24)	1.3 mm <sup>2</sup> (AWG16)
Motor output	0.2 mm <sup>2</sup> (AWG24)	1.3 mm <sup>2</sup> (AWG16)
Digital inputs	0.08 mm <sup>2</sup> (AWG28)	0.5 mm <sup>2</sup> (AWG20)
Digital output	0.08 mm <sup>2</sup> (AWG28)	0.5 mm <sup>2</sup> (AWG20)

## Verify the installation


- Check all connections: Power supply, Stepper motor and control logics.
- Make sure that all settings are correct for the application.
- Make sure that the characteristics of the DC power supply are appropriate for the drive.
- If possible, remove the load from the rotor of the motor to avoid wrong movements and eventual damages.
- Supply power and make sure that the green led is on or blinking. If the led is OFF, shut down immediately and check if all connections are correct.
- Enable the current in the motor (without STEP Clock) and, if possible, verify the presence of the Holding Torque.
- Execute a movement of some steps and verify if the rotation direction is the desired one.

 *If the motion direction is not the desired one, it is possible to change it leaving the DIR input unchanged and reversing the connection of a single phase of the motor to CN1, for example A with Av.*


- Disconnect the power supply, fix the motor to the load and check the full functionality.

## Analysis of malfunctions

When any of the following situations occur, the drive is placed in a fault condition.

	DEFECT	CAUSE	ACTION
	Intervention of the thermal protection.	Can be caused due to a heavy working cycle or a high current in the motor.	Improve the drive cooling by a decent air flow or a fan. Consider to use a motor with a higher torque vs. current rating.
	Intervention of the current protection.	Short circuit to the motor output stage(s) of the drive.	Check motor windings and cables and remove the short circuits replacing the faulty cables or the motor if necessary.
	Intervention of the over/under voltage protection.	Supply voltage out of range.	Check the value of the supply voltage.
	Open phase motor protection.	Open circuit from motor windings and drive.	Check motor cables and connections to the drive.

At any of the following situations occur, the drive doesn't work and isn't placed in an error condition.

	DEFECT	CAUSE	ACTION
	Noisy motor movement with vibrations.	Can be caused due to a lack of power supply to a phase of the motor, a poor regulation of the winding currents.	Check the cables and connections of the motor and/or change the motor speed to exit a resonance region.
	The external fuse on the power supply of the drive is burned	Can be caused by a wrong connection of the power supply.	Connect the power supply correctly and replace the fuse.
	At high speed, the motor torque is not enough.	It can be due to a motor current self-limitation.	Increase the motor current (always within the limits), increase the supply voltage, change motor connection from series to parallel.

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